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| **Deep learning architectures** | GET: Group Event Transformer for Event-Based Vision *Yansong Peng, Yueyi Zhang, Zhiwei Xiong, Xiaoyan Sun, Feng Wu* Paper ID:4816 - Location: Room "Nord" - 161 |
| **Motion estimation, matching and tracking** | TMA: Temporal Motion Aggregation for Event-based Optical Flow Haotian Liu, Guang Chen, Sanqing Qu, Yanping Zhang, Zhijun Li, Alois Knoll, Changjun Jiang Paper ID:9515 - Location: Room "Foyer Sud" - 019 |
| **Motion estimation, matching and tracking** | Taming Contrast Maximization for Learning Sequential, Low-latency, Event-based Optical Flow Federico Paredes-Vallés, Kirk Y. W. Scheper, Christophe De Wagter, Guido C. H. E. de Croon Paper ID:10716 - Location: Room "Foyer Sud" - 020 |
| **Motion estimation, matching and tracking** | Event-based Temporally Dense Optical Flow Estimation with Sequential Learning Wachirawit Ponghiran, Chamika Mihiranga Liyanagedera, Kaushik Roy Paper ID:7095 - Location: Room "Foyer Sud" - 032 |
| **Computational imaging** | Generalizing Event-Based Motion Deblurring in Real-World Scenarios Xiang Zhang, Lei Yu, Wen Yang, Jianzhuang Liu, Gui-Song Xia Paper ID:6077 - Location: Room "Foyer Sud" - 086 |
| **Transfer, low-shot, continual, long-tail learning 2** | Unsupervised Domain Adaptation for Training Event-Based Networks Using Contrastive Learning and Uncorrelated Conditioning Dayuan Jian, Mohammad Rostami Paper ID:8743 - Location: Room "Foyer Sud" - 106 |
| **Machine learning and dataset** | Label-Free Event-based Object Recognition via Joint Learning with Image Reconstruction from Events Hoonhee Cho, Hyeonseong Kim, Yujeong Chae, Kuk-Jin Yoon Paper ID:5805 - Location: Room "Foyer Sud" - 175 |

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| **3D from multi-view and sensors 1** | Deformable Neural Radiance Fields using RGB and Event Cameras *Qi Ma, Danda Pani Paudel, Ajad Chhatkuli, Luc Van Gool* Paper ID:9284 - Location: Room "Foyer Sud" - 136 |
| **Low-level vision and theory** | A 5-Point Minimal Solver for Event Camera Relative Motion Estimation Ling Gao, Hang Su, Daniel Gehrig, Marco Cannici, Davide Scaramuzza, Laurent Kneip Paper ID:12412 - Location: Room "Paris Nord" |
| **Motion estimation, matching and tracking** | Learning Optical Flow from Event Camera with Rendered Dataset Xinglong Luo, Kunming Luo, Ao Luo, Zhengning Wang, Ping Tan, Shuaicheng Liu Paper ID:6964 - Location: Room "Foyer Sud" - 034 |
| **Computational imaging** | Event Camera Data Pre-training Yan Yang, Liyuan Pan, Liu Liu Paper ID:1207 - Location: Room "Foyer Sud" - 083 |
| **Computational imaging** | Unsupervised Video Deraining with An Event Camera Jin Wang, Wenming Weng, Yueyi Zhang, Zhiwei Xiong Paper ID:3186 - Location: Room "Foyer Sud" - 095 |
| **Vision applications and systems** | Time-to-Contact Map by Joint Estimation of Up-to-Scale Inverse Depth and Global Motion using a Single Event Camera Urbano Miguel Nunes, Laurent Udo Perrinet, Sio-Hoi Ieng Paper ID:1746 - Location: Room "Foyer Sud" - 159 |